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12/18/80

Continuous Hamiltonian
Systems: The Equations of
Ideal MHD & Vlasov

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OVERVIEW

1. REVIEW OF HAMILTONIAN Systems
2. Generalization
3. KdV Equation
4. MHD
5. Vlasov-Poisson
6. Possibilities & Avenues

1. Review

§ 1.1 Usual Approach

P.E. & K.E. \Rightarrow

$$L(q, \dot{q}) \xrightarrow{\text{Legendre}} H(q, p)$$

$$\dot{q}_R = \frac{\partial H}{\partial p_R} \quad \dot{p}_R = - \frac{\partial H}{\partial q_R}$$

$$R = 1, 2, \dots, N$$

§ 1.2 Why Beneficial

- Dynamics contained in H instead of $2N$ functions
- Transformation theory $Q_R = Q_R(\underline{p}, \underline{q})$
& $P_R = P_R(\underline{p}, \underline{q})$ involves one function -
Mixed Variable generating function or Lie

"Harmonic Analysis as the Exploitation of Sym."
G.W. Mackey, Bull. AMS, V.3, #1 (1980) pp. 543
- 696

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§1.3 Axiomatic Approach

$$[A, B] = \sum_K \left[\frac{\partial A}{\partial q_K} \frac{\partial B}{\partial p_K} - \frac{\partial B}{\partial q_K} \frac{\partial A}{\partial p_K} \right]$$

$$\dot{q}_K = [q_K, H]$$

$$\dot{p}_K = [p_K, H]$$

$$\text{let } \underline{z}^i = \begin{cases} q_K & i = K = 1, 2, \dots, N \\ p_K & i = K+N = N+1, \dots, 2N \end{cases}$$

$$\dot{\underline{z}}^i = [\underline{z}^i, H] \quad \& \quad [A, B] = \frac{\partial A}{\partial \underline{z}^i} \underbrace{J^{ij}} \frac{\partial B}{\partial \underline{z}^j}$$

$$\text{where } (J^{ij}) = \begin{bmatrix} 0 & I_N \\ -I_N & 0 \end{bmatrix}$$

$$\bar{\underline{z}}^i = \bar{\underline{z}}^i(\underline{z}) \Rightarrow$$

$$\bar{J}^{ij} = J^{rs} \frac{\partial \bar{\underline{z}}^i}{\partial \underline{z}^r} \frac{\partial \bar{\underline{z}}^j}{\partial \underline{z}^s} \quad \text{if}$$

$$\bar{J} = J \quad \text{canonical}$$

Properties of Bracket

$$(i) [A, B] = -[B, A]$$

$$(ii) [\lambda A, B] = \lambda [A, B]$$

$$(iii) [A, [B, C]] + [B, [C, A]] + [C, [A, B]] = 0$$

$[A+B, C] = [A, C] + [B, C]$
Antisymmetry

Bilinearity

Jacobi Id.

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$J^{ij} = [z^i, z^j] \Rightarrow$ Jacobi Identity

$$S^{ijk} = J^{ie} \frac{\partial}{\partial z^e} J^{jk} + J^{je} \frac{\partial}{\partial z^e} J^{ki} + J^{ke} \frac{\partial}{\partial z^e} J^{ij}$$

$$\vec{S}^{ijk} = S^{prs} \frac{\partial \bar{z}^i}{\partial z^r} \frac{\partial \bar{z}^j}{\partial z^s} \frac{\partial \bar{z}^k}{\partial z^s}$$

$$S = 0 \Rightarrow \vec{S} = 0$$

Vector space of functions (over \mathbb{R})
w/ Poisson Bracket product defines
Lie Algebra. Ex. Vectors in E^3 w/ cross Pdt.

Axiomatic Approach

- Forget about canonical variables
concentrate on algebraic properties
- Find Hamiltonian, "Guess" bracket
(Easier than finding canonical variables)
- Darboux Theorem \Rightarrow Canonical variables exist
(1882)

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- Noncanonical Variables may be better for perturbation theory.

R. Littlejohn, J. Math. Phys. 20, 2445 (1979).

§ 1.4 Continuous Hamiltonian Systems

$N \rightarrow \infty$, PDE's

H. Goldstein, Classical Mech., Ch. 11

$$[\hat{A}, \hat{B}] = \sum_k \int \left(\frac{\delta \hat{A}}{\delta \pi_k} \frac{\delta \hat{B}}{\delta q_k} - \frac{\delta \hat{B}}{\delta \pi_k} \frac{\delta \hat{A}}{\delta q_k} \right) dz$$

$$= \int \frac{\delta \hat{A}}{\delta u^i} O^{ij} \frac{\delta \hat{B}}{\delta u^j} dz = \left\langle \frac{\delta \hat{A}}{\delta u^i} \middle| O^{ij} \frac{\delta \hat{B}}{\delta u^j} \right\rangle$$

$$(O^{ij}) = \begin{bmatrix} 0 & I_N \\ -I_N & 0 \end{bmatrix} \quad \text{cosymplectic density}$$

- Darboux for ∞ dimensions?

J. Marsden, private communication

6-A

2. References

Y. Manin, J. Soviet Math., 11 (1979) p. 1

B. Kupershmidt, Lect. Notes in Math, 755.

P.R. Chernoff & J. Marsden, Lect. Notes in Math., 425, S. Verlag 1974

Abraham & J. Marsden, ch. 4, Foundations of Mech. Benjamin.

I. Gelfand & I. Dorfman, Func. Anal. & App., 13 (1979)
p. ~~247~~ 248

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2. Generalization

§2.1 Preliminary Specification

$$\frac{\partial u^i(\underline{x}, t)}{\partial t} = F^i(\underline{u}, \underline{x}) \quad i = 1, 2, \dots, N$$

u^i is defined on $T \times V$
 where $T \subset \mathbb{R}$ & $V \subset \mathbb{R}^m$

Suppose F^i is an operator composed of C^∞ functions of t he following:

a) $\underline{u} \in \underline{x}$

b) $u_{\underline{k}}^i \triangleq \frac{\partial^k u^i}{\partial x_1^{k_1} \partial x_2^{k_2} \dots \partial x_m^{k_m}} ; k = |\underline{k}| = \sum_{i=1}^m k_i,$
 $k_i \in \mathbb{Z}^+$

c) $u_{\underline{k}}^i \triangleq \int_{x_1}^{x_1^{k_1}} \int_{x_2}^{x_2^{k_2}} \dots \int_{x_m}^{x_m^{k_m}} u^i (dx_1)^{k_1} (dx_2)^{k_2} \dots (dx_m)^{k_m}$

d) $\int_V K(\underline{x} | \underline{x}') f(\underline{u}_{\underline{k}}, \underline{u}_{-\underline{k}}) d\underline{x}'$

Call Class of Operators \mathcal{L}

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§ 2.2 Two Vector Spaces

a) Suppose solutions $u^i(x, z)$ are elements of ω , vector space of functions of \underline{x} .

Define inner product by

$$\langle f | g \rangle = \int_V f g dz$$

b) Vector space, Ω , whose elements are functionals of the form

$$\hat{F}\{\underline{u}\} = \int_V F(\underline{u}) dz$$

where $F \in \mathcal{L}$

EXAMPLES

a) if $f, g(\underline{u})$

$$\langle f | g \rangle \in \underline{\Omega}$$

b) $\hat{H}\{g, u\} = \int_V (\frac{1}{2} g u^2 + g u) dz$

$$\in \underline{\Omega}$$

(8)

§ 2.3 DEFINITION.

A system is Hamiltonian if the following hold:

a) \exists an integral invariant

$$\hat{H}\{\underline{u}\} = \int_V H(\underline{u}) d\tau \in \Omega$$


s. t.

$$\frac{\partial \hat{H}}{\partial t} + \sum_i^N \frac{\partial}{\partial x_i} J^i = 0$$

b) Can write equations in the form

$$\frac{\partial u^i}{\partial t} = O^{ij} \frac{\delta \hat{H}}{\delta u^j} \quad i, j = 1, 2, \dots, N$$

where $\frac{\delta \hat{H}}{\delta u^j}$ is the functional

derivative defined by 

$$\textcircled{9} \quad \left. \frac{d}{d\epsilon} \hat{F}\{u^i + \epsilon w\} \right|_{\epsilon=0} \equiv \left\langle \frac{\delta \hat{F}}{\delta u^i} \mid w \right\rangle$$

EXAMPLES

$$a) \quad \hat{L}\{q\} = \int \mathcal{L}(q, \dot{q}) dt$$

$$\left. \frac{d}{d\epsilon} \hat{L}\{q + \epsilon w\} \right|_{\epsilon=0} = \int w \left(\frac{\partial \mathcal{L}}{\partial q} - \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{q}} \right) dt$$

$$= \int w \frac{\delta \hat{L}}{\delta q}$$

$$b) \quad \hat{F}\{u\} = \int F(u, u_x, u_{xx}, \dots) dx$$

$$\frac{\delta \hat{F}}{\delta u} = \frac{\partial F}{\partial u} - \frac{d}{dx} \frac{\partial F}{\partial u_x} + \frac{d^2}{dx^2} \frac{\partial F}{\partial u_{xx}} - \dots$$

$$c) \quad \hat{F}\{u\} = u(x) = \int u(x') \delta(x-x') dx'$$

$$\frac{\delta \hat{F}}{\delta u(x')} = \delta(x-x')$$

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c) O^{ij} via bracket makes Ω a Lie Algebra

Recall

$$[\hat{F}, \hat{G}] = \left\langle \frac{\delta \hat{F}}{\delta u^i} \middle| O^{ij} \frac{\delta \hat{G}}{\delta u^j} \right\rangle$$

$$[\hat{F}, \hat{G}] : \Omega \times \Omega \rightarrow \Omega$$

$$i) [\hat{F}, \hat{G}] = -[\hat{G}, \hat{F}] \quad \forall \hat{F}, \hat{G} \in \Omega$$

$\iff O^{ij}$ is anti-self-adjoint

ii) Jacobi Identity

$$[\hat{E}, [\hat{F}, \hat{G}]] + [\hat{F}, [\hat{G}, \hat{E}]] + [\hat{G}, [\hat{E}, \hat{F}]] = 0$$

$$\forall \hat{F}, \hat{G}, \hat{E} \in \Omega$$

If the above hold then can write system in Heisenberg form

$$\frac{\partial u^i}{\partial t} = [u^i, \hat{H}]$$

(11)

§ 2.4 Jacobi Identity

P. Lax, Comm. Pure Appl. Math., 28
(1975) 141.

Recall $\frac{d}{d\epsilon} \hat{F}\{u^i + \epsilon w\} \Big|_{\epsilon=0} = \left\langle \frac{\delta \hat{F}}{\delta u^i} \Big| w \right\rangle \triangleq \hat{G}$
 $\epsilon=0$ $\epsilon \in \Omega$

Do it again

$$\frac{d \hat{G}\{u^j + \epsilon z\}}{d\eta} \Big|_{\eta=0} = \left\langle \frac{\delta \hat{G}}{\delta u^j} \Big| z \right\rangle$$
$$\triangleq \left\langle \frac{\delta^2 \hat{F}}{\delta u^j \delta u^i} z \Big| w \right\rangle$$

By symmetry operator $\frac{\delta^2 \hat{F}}{\delta u^j \delta u^i}$ has
property

$$\left\langle \frac{\delta^2 \hat{F}}{\delta u^i \delta u^j} z \Big| w \right\rangle = \left\langle z \Big| \frac{\delta^2 \hat{F}}{\delta u^j \delta u^i} w \right\rangle$$

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EXAMPLE

$$\hat{F}(u) = \int F(u, u_x) dx$$

$$\hat{G} = \frac{d}{d\epsilon} \hat{F}(u + \epsilon w) \Big|_{\epsilon=0} = \left\langle \frac{\delta \hat{F}}{\delta u} \mid w \right\rangle = \left\langle \frac{\delta F}{\delta u} - \frac{d}{dx} \frac{\delta F}{\delta u_x} \mid w \right\rangle$$

$$= \left\langle \frac{\delta F}{\delta u} - \frac{\delta^2 F}{\delta u \delta u_x} u_x - \frac{\delta^2 F}{\delta u_x^2} u_{xx} \mid w \right\rangle$$

$$\frac{d}{d\eta} \hat{G}(u + \eta z) \Big|_{\eta=0} = \left\langle \frac{\delta^2 F}{\delta u^2} z + \frac{\delta^2 F}{\delta u \delta u_x} z_x \right.$$

$$\left. - \frac{\delta^3 F}{\delta u^2 \delta u_x} u_x z - \frac{\delta^3 F}{\delta u \delta u_x^2} u_x z_x - \frac{\delta^3 F}{\delta u_x^3} z_x \right.$$

$$\left. - \frac{\delta^3 F}{\delta u^2 \delta u_x^2} u_{xx} z - \frac{\delta^3 F}{\delta u \delta u_x} u_{xx} z_x - \frac{\delta^3 F}{\delta u_x^2} z_{xx} \mid w \right\rangle$$

$$= \left\langle \frac{\delta^2 \hat{F}}{\delta u^2} z \mid w \right\rangle = \left\langle z \mid \frac{\delta^2 \hat{F}}{\delta u^2} w \right\rangle$$

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$$\frac{d}{d\epsilon} \langle \hat{F}, \hat{G} | (u^2 + \epsilon w) \rangle_{\epsilon=0} = \left\langle \frac{\delta \langle \hat{F}, \hat{G} \rangle}{\delta u^2} \middle| w \right\rangle$$

$$= \frac{d}{d\epsilon} \left\langle \underbrace{\frac{\delta \hat{F}}{\delta u^2}}_{(1)} \middle| \underbrace{0^{ij}}_{(3)} \underbrace{\frac{\delta \hat{G}}{\delta u^i}}_{(2)} \right\rangle (u^2 + \epsilon w) \Big|_{\epsilon=0}$$

$$= \left\langle \frac{\delta^2 \hat{F}}{\delta u^2 \delta u^i} \middle| w \right\rangle \underbrace{0^{ij} \frac{\delta \hat{G}}{\delta u^j}}_{(1)} + \left\langle \frac{\delta \hat{F}}{\delta u^i} \middle| \underbrace{0^{ij} \frac{\delta^2 \hat{G}}{\delta u^i \delta u^j}}_{(2)} \middle| w \right\rangle$$

$$+ \left\langle \frac{\delta \hat{F}}{\delta u^i} \middle| \underbrace{\frac{\delta 0^{ij}}{\delta u^2}}_{(3)} (w) \frac{\delta \hat{G}}{\delta u^j} \right\rangle$$

ISOLATING W \Rightarrow

$$\frac{\delta \langle \hat{F}, \hat{G} \rangle}{\delta u^2} = \underbrace{\frac{\delta^2 \hat{F}}{\delta u^2 \delta u^i}}_{(1)} 0^{ij} - \underbrace{\frac{\delta^2 \hat{G}}{\delta u^i \delta u^j}}_{(2)} 0^{ij} \frac{\delta \hat{F}}{\delta u^i}$$

$$+ \underbrace{K^{ij}}_{(3)} \left(\frac{\delta \hat{F}}{\delta u^i}, \frac{\delta \hat{G}}{\delta u^j} \right)$$

(14)

Obtain for Jacobi

$$S = \left\langle \frac{\delta \hat{E}}{\delta u^m} \middle| O^{m\alpha} \frac{\delta (E, \hat{C})}{\delta u^\alpha} \right\rangle + \text{cyc.}$$

using operator symmetries

$$S = \left\langle \frac{\delta \hat{E}}{\delta u^m} \middle| O^{m\alpha} K_{\alpha}^{ij} \left(\frac{\delta \hat{E}}{\delta u^i}, \frac{\delta \hat{C}}{\delta u^j} \right) \right\rangle + \text{cyc.}$$

compare with

$$S^{ijk} = \sum_{l \neq i} J^{il} \frac{\partial}{\partial u^l} J^{jk} + \text{cyc.}$$

for F. D. F. case

Th. If operator C^{ij} does not depend upon the u^i , then Jacobi is immediate.

(15)

3. KdV Equation

C. S. Gardner, J. Math. Phys. 12, 1548
(1971).

$$u_t = -u u_x - \beta u_{xxx}$$

The following is conserved

$$\hat{H}\{u\} = \int \left(\beta \frac{u_x^2}{2} - \frac{u^3}{6} \right) dx$$

Gardner bracket:

$$[\hat{F}, \hat{G}] = \int \frac{\delta \hat{F}}{\delta u} \frac{d}{dx} \frac{\delta \hat{G}}{\delta u} dx$$

Lie properties, including Jacobi, are immediate.

$$u_t = [u, \hat{H}] = -\frac{d}{dx} \left(\frac{u^2}{2} + \beta u_{xx} \right)$$

Note form of bracket:

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4. Ideal MHD

P. J. Morrison & J. M. Greene, Phys. Rev. Lett. 45, 790 (1980).

§ 4.1 Equations

$$\underline{U}_{\pm} = -\nabla \frac{U^2}{2} + \underline{U} \times (\nabla \times \underline{U}) - \frac{1}{\rho} \nabla (\rho^2 U_{\parallel})$$

$$\underline{F}_{\pm} = -\nabla \cdot (\rho \underline{U}) + \frac{1}{\rho} (\nabla \times \underline{B}) \times \underline{B}$$

$$\underline{E}_{\pm} = \nabla \times (\underline{U} \times \underline{B})$$

$$S_{\pm} = -\underline{U} \cdot \nabla S$$

$$U(\rho, S) \triangleq \frac{\text{Internal Energy}}{\text{Mass}}$$

$$S \triangleq \frac{\text{Entropy}}{\text{Mass}}$$

$$p = \rho^2 U_{\rho}$$

$$T = U_S$$

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§4.2 Bracket

$$\hat{H} = \int_V \left(\frac{1}{2} \rho u^2 + \rho U(\rho, S) + \frac{B^2}{2} \right) d^3x$$

$$\begin{aligned}
 [\hat{F}, \hat{G}] = & - \int_V \left\{ \left[\frac{\delta \hat{F}}{\delta \rho} \cdot \nabla \cdot \frac{\delta \hat{G}}{\delta \underline{u}} + \frac{\delta \hat{F}}{\delta \underline{u}} \cdot \nabla \frac{\delta \hat{G}}{\delta \rho} \right] \right. \\
 & + \left[\frac{1}{\rho} \frac{\delta \hat{F}}{\delta \underline{u}} \cdot (\nabla \times \underline{u}) \times \frac{\delta \hat{G}}{\delta \underline{u}} \right] \\
 & \left. + \left[\frac{\nabla S}{\rho} \cdot \left(\frac{\delta \hat{F}}{\delta S} \frac{\delta \hat{G}}{\delta \underline{u}} - \frac{\delta \hat{G}}{\delta S} \frac{\delta \hat{F}}{\delta \underline{u}} \right) \right] \right\} d^3x \\
 & + \int_V \left\{ \left[\frac{1}{\rho} \frac{\delta \hat{F}}{\delta \underline{u}} \cdot \underline{B} \times (\nabla \times \frac{\delta \hat{G}}{\delta \underline{u}}) \right] + \left[\frac{\delta \hat{F}}{\delta \underline{u}} \cdot \nabla \times \left(\frac{\underline{B}}{\rho} \times \frac{\delta \hat{G}}{\delta \underline{u}} \right) \right] \right\} d^3x
 \end{aligned}$$

let $\rho = x^0, S = x^1, \underline{u} = (x^2, x^3, x^4)$

& $\underline{B} = (x^5, x^6, x^7)$ then

$$= \int_V \frac{\delta \hat{F}}{\delta x^i} \delta^{ij} \frac{\delta \hat{G}}{\delta x^j} = \left\langle \frac{\delta \hat{F}}{\delta x^i} \middle| \delta^{ij} \middle| \frac{\delta \hat{G}}{\delta x^j} \right\rangle$$

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§ 4.3 Canonical Variables

$$\text{let } \underline{u} = \frac{\underline{B} \times (\underline{\nabla} \times \underline{A})}{\rho} + \underline{\nabla} \phi$$

$$+ \frac{\psi \underline{\nabla} S}{\rho}$$



$$[\hat{F}, \hat{G}] = \int_V \left\{ \left[\frac{\delta \hat{G}}{\delta \phi} \frac{\delta \hat{F}}{\delta \rho} - \frac{\delta \hat{F}}{\delta \phi} \frac{\delta \hat{G}}{\delta \rho} \right] \right.$$

$$\left. + \left[\frac{\delta \hat{F}}{\delta S} \frac{\delta \hat{G}}{\delta \psi} - \frac{\delta \hat{G}}{\delta S} \frac{\delta \hat{F}}{\delta \psi} \right] + \left[\frac{\delta \hat{G}}{\delta \underline{A}} \frac{\delta \hat{F}}{\delta \underline{B}} - \frac{\delta \hat{F}}{\delta \underline{A}} \frac{\delta \hat{G}}{\delta \underline{B}} \right] \right\} d^3x$$

§ 4.4 Conservation Form

$$\text{let } \underline{M} = \rho \underline{u} \quad \text{and} \quad \sigma = \rho S$$

↑
Momentum
density

↑
Specific Entropy

⇒ § Conservation Eqs.

(A)

Bracket Becomes

$$\begin{aligned}
 (\hat{F}, \hat{G}) = -\int d^2x \bigg\{ & \delta \left[\frac{\delta \hat{F}}{\delta \pi} \cdot \nabla \hat{\sigma} - \hat{\sigma} \cdot \nabla \frac{\delta \hat{F}}{\delta \pi} \right] \\
 + \text{II} \cdot & \left[\frac{\delta \hat{F}}{\delta \pi} \cdot \nabla \hat{\sigma} - \hat{\sigma} \cdot \nabla \frac{\delta \hat{F}}{\delta \pi} \right] \\
 + \text{III} \cdot & \left[\frac{\delta \hat{F}}{\delta \pi} \cdot \nabla \hat{\sigma} - \hat{\sigma} \cdot \nabla \frac{\delta \hat{F}}{\delta \pi} \right] \\
 + \text{IV} \cdot & \left[\frac{\delta \hat{F}}{\delta \pi} \cdot \nabla \hat{\sigma} - \hat{\sigma} \cdot \nabla \frac{\delta \hat{F}}{\delta \pi} \right] \\
 \bigg\} & + \left(\left[\frac{\delta \hat{F}}{\delta \pi} \cdot \nabla \hat{\sigma} - \hat{\sigma} \cdot \nabla \frac{\delta \hat{F}}{\delta \pi} \right] \right) \cdot \hat{E} +
 \end{aligned}$$

(20)

5. Vlasov - Poisson

P. J. Morrison, PPPL R-1702 (1960).

To appear in Phys. Lett. A.

§ 5.1 Equations

$$\frac{\partial f(x, u, t)}{\partial t} = -u \cdot \frac{\partial f}{\partial x} - E \cdot \frac{\partial f}{\partial u} = 0$$

$$\frac{\partial E}{\partial x} = \int f \, du$$



$$\frac{\partial f}{\partial t} = -u \cdot \frac{\partial f}{\partial x} + \frac{\partial}{\partial x} \int \frac{f(x', u', t)}{|x-x'|} dx' du'$$

let $z = (x, u)$

$$\hat{H}\{f\} = \int H_1(z) f(z) dz + \frac{1}{2} \iint \frac{f(z) f(z')}{|z-z'|} H_2(z/z') \times dz dz'$$

$$H_1 = \frac{1}{2} m u^2 ; \quad H_2 = \frac{1}{|x-x'|}$$

(21)

§ 5.2 Bracket

$$[\hat{F}, \hat{G}] = \int f \left\{ \frac{\delta \hat{F}}{\delta f}, \frac{\delta \hat{G}}{\delta f} \right\} dz$$

$$\text{where } \{f, g\} = \frac{\partial f}{\partial x} \cdot \frac{\partial g}{\partial y} - \frac{\partial g}{\partial x} \cdot \frac{\partial f}{\partial y}$$

Observe

$$\int f \left\{ \frac{\delta \hat{F}}{\delta f}, \frac{\delta \hat{G}}{\delta f} \right\} dz = - \int \frac{\delta \hat{F}}{\delta f} \left\{ f, \frac{\delta \hat{G}}{\delta f} \right\} dz$$

$$\frac{\delta \hat{H}}{\delta f} = H_p$$

§ 5.3 Jacobi Identity

$$\frac{\delta [\hat{F}, \hat{G}]}{\delta f} = \left\{ \frac{\delta \hat{F}}{\delta f}, \frac{\delta \hat{G}}{\delta f} \right\} + \text{quater terms}$$

$$\begin{aligned} S &= [\hat{E}, [\hat{F}, \hat{G}]] + \text{cyc} = \int f \left\{ \frac{\delta \hat{E}}{\delta f}, \frac{\delta [\hat{F}, \hat{G}]}{\delta f} \right\} dz + \text{cyc} \\ &= \int f \left\{ \frac{\delta \hat{E}}{\delta f}, \left\{ \frac{\delta \hat{F}}{\delta f}, \frac{\delta \hat{G}}{\delta f} \right\} \right\} dz + \text{cyc} = 0 \end{aligned}$$

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6. Possibilities & Avenues

- Maxwell-Vlasov
- Relativistic Maxwell-Vlasov
- 1-D Fluid, ∞ conservation laws, dual Hamiltonian
- Approx. schemes which preserve Hamiltonian form. Discretization & Truncation.
- Unending search for conservation laws
- 1-D Fluid w/ Entropy
- 2-D MHD