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Bulletin of the American Physical Society

Volume 26, Number 7, September 1981

PROGRAM OF THE 23rd ANNUAL MEETING
OF THE DIVISION OF PLASMA PHYSICS
IN NEW YORK, N. Y., 12-16 OCTOBER 1981

6R13 Rayleigh-Ritz Procedure for the Eulerian Vlasov-Poisson Equations.* P. J. MORRISON, Princeton U. -- Recently it was shown that the Vlasov-Poisson equations possess underlying Hamiltonian structure.¹ The canonical version of these equations can readily be shown to arise from a variational principle, which serves as a starting point for the Rayleigh-Ritz numerical procedure. The variational integral is discretized by a selection of finite elements with nodal density prearranged for accuracy. Such a discretization is singled out; there is no arbitrariness in the selection of basis functions as for the Galerkin method. The evolution equations for the system, a finite set of ordinary differential equations, are obtained by variation of this discretized integral. We anticipate that this variational principle will also be useful for multiple time scale approximation techniques.

*This work supported by DoE DE-AC02-CHO-3073.

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1. P. J. MORRISON, Princeton Plasma Lab. Report #1788 (1981).

Published by The American Physical Society
through the American Institute of Physics

RAYLEIGH - RITZ
PROCEDURE FOR THE
EULERIAN VLASOV-
POISSON EQUATIONS

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APS 1981

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Rayleigh-Ritz Procedure for the Eulerian Vlasov-Poisson Equations.* P. J. MORRISON, Princeton U. -- Recently it was shown that the Vlasov-Poisson equations possess underlying Hamiltonian structure.¹ The canonical version of these equations can readily be shown to arise from a variational principle, which serves as a starting point for the Rayleigh-Ritz numerical procedure. The variational integral is discretized by a selection of finite elements with nodal density prearranged for accuracy. Such a discretization is singled out; there is no arbitrariness in the selection of basis functions as for the Galerkin method. The evolution equations for the system, a finite set of ordinary differential equations, are obtained by variation of this discretized integral. We anticipate that this variational principle will also be useful for multiple time scale approximation techniques.

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Definition: A system is Hamiltonian if it can be written in the form

$$\frac{\partial X^i}{\partial t} = \dot{F}^i(X) = \underline{[X^i, H]}$$

where $[,]$ operates on functionals (e.g. $\int \frac{1}{2} p v^2 dz$) and satisfies

* bilinear

* Antisymmetric $[A, B] = -[B, A]$

* Jacobi Condition $[[A, B], C] + [[B, C], A] + [[C, A], B] = 0$

Maxwell - Vlasov System

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$$\underline{B}_t = -\nabla \times \underline{E} \quad \underline{E}_t = \nabla \times \underline{B} - \sum_{\alpha} e_{\alpha} \int \underline{v} f_{\alpha} d\underline{v}$$

$$f_{\alpha t} = -\underline{v} \cdot \frac{\partial f_{\alpha}}{\partial \underline{x}} - \frac{e_{\alpha}}{m_{\alpha}} (\underline{E} + \underline{v} \times \underline{B}) \cdot \frac{\partial f_{\alpha}}{\partial \underline{v}}$$

$$H(f, \underline{E}, \underline{B}) = \sum_{\alpha} \int \frac{1}{2} m_{\alpha} v^2 f_{\alpha} d\underline{v} + \int \frac{\underline{E}^2 + \underline{B}^2}{2} d\underline{x}$$

$$[A, B] = \sum_{\alpha} \int \frac{f_{\alpha}}{m_{\alpha}} \left\{ \frac{\delta A}{\delta f_{\alpha}}, \frac{\delta B}{\delta f_{\alpha}} \right\} d\underline{v} + \frac{e_{\alpha}}{m_{\alpha}} \int \left(\frac{\delta A}{\delta \underline{E}} \cdot \frac{\partial f_{\alpha}}{\partial \underline{v}} \frac{\delta B}{\delta f_{\alpha}} - \frac{\delta B}{\delta \underline{E}} \cdot \frac{\partial f_{\alpha}}{\partial \underline{v}} \frac{\delta A}{\delta f_{\alpha}} \right) d\underline{v}$$

$$+ \frac{e_{\alpha}}{m_{\alpha}} \int \underline{B} \cdot \left(\frac{\partial}{\partial \underline{v}} \frac{\delta A}{\delta f_{\alpha}} \times \frac{\partial}{\partial \underline{v}} \frac{\delta B}{\delta f_{\alpha}} \right) d\underline{v} + \int \left(\frac{\delta A}{\delta \underline{B}} \cdot \nabla \times \frac{\delta B}{\delta \underline{B}} - \frac{\delta B}{\delta \underline{B}} \cdot \nabla \times \frac{\delta A}{\delta \underline{B}} \right) d\underline{x}$$

where $\{f, g\} = \frac{\partial f}{\partial \underline{x}} \cdot \frac{\partial g}{\partial \underline{v}} - \frac{\partial g}{\partial \underline{x}} \cdot \frac{\partial f}{\partial \underline{v}}$

Vlasov-Poisson

$$[A, B] = \sum_{\alpha} \int \frac{f_{\alpha}}{m_{\alpha}} \left\{ \frac{\delta A}{\delta f_{\alpha}}, \frac{\delta B}{\delta f_{\alpha}} \right\} dz$$

where $\{f, g\} = f_x \cdot g_v - f_v \cdot g_x$

$$H = \sum_{\alpha} \int \frac{1}{2} m_{\alpha} v^2 f_{\alpha} dz - \frac{1}{2} \sum_{\alpha, \beta} e_{\alpha} e_{\beta} \iint K(x|x') f_{\alpha}(z) f_{\beta}(z') dz dz'$$

ONE Dynamical Eq. (per species)

$$\frac{\partial f_{\alpha}}{\partial t} = - \underline{W}_{\alpha} \cdot \frac{\partial f_{\alpha}}{\partial \underline{z}} \quad \underline{z} = (x, v)$$

where $\underline{W}_{\alpha} = (v, \frac{e_{\alpha}}{m_{\alpha}} \frac{\partial}{\partial x} \sum_{\beta} \int K(x|x') f_{\beta}(z') dz')$

$$\nabla_{\underline{p}} \cdot \underline{W}_{\alpha} = 0$$

CANONICAL VARIABLES

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$$\text{Let } f_\alpha = \{ \Psi_\alpha, \mathcal{I}_\alpha \} = \frac{\partial \Psi_\alpha}{\partial x} \cdot \frac{\partial \mathcal{I}_\alpha}{\partial v} - \frac{\partial \mathcal{I}_\alpha}{\partial x} \cdot \frac{\partial \Psi_\alpha}{\partial v}$$

obtain

$$\frac{\partial \Psi_\alpha}{\partial t} = \frac{\delta H}{\delta \mathcal{I}_\alpha} \quad \& \quad \frac{\partial \mathcal{I}_\alpha}{\partial t} = - \frac{\delta H}{\delta \Psi_\alpha}$$



$$\frac{\partial \Psi_\alpha}{\partial t} = - \underline{W}_\alpha \cdot \nabla_p \Psi_\alpha$$

$$\frac{\partial \mathcal{I}_\alpha}{\partial t} = - \underline{W}_\alpha \cdot \nabla_p \mathcal{I}_\alpha$$

Recall

$$\underline{W}_\alpha = \left(v, \frac{e_\alpha}{m_\alpha} \frac{\partial}{\partial x} \sum_\beta e_\beta \int \kappa(x|x') f_\beta(z') dz' \right)$$

Action

$$J = \sum_{\alpha} \int dt \left\{ \int \gamma_{\alpha} \frac{\partial \Psi_{\alpha}}{\partial t} dz \right.$$

$$- \int \frac{1}{2} m_{\alpha} v^2 \left[\frac{\partial \Psi_{\alpha}}{\partial x} \frac{\partial \gamma_{\alpha}}{\partial u} - \frac{\partial \gamma_{\alpha}}{\partial x} \frac{\partial \Psi_{\alpha}}{\partial u} \right] dz$$

$$+ \frac{1}{2} \sum_{\alpha} \sum_{\beta} e_{\alpha} e_{\beta} \iint K(x|x') \left[\frac{\partial \Psi_{\alpha}}{\partial x} \frac{\partial \gamma_{\alpha}}{\partial u} - \frac{\partial \gamma_{\alpha}}{\partial x} \frac{\partial \Psi_{\alpha}}{\partial u} \right] \left[\frac{\partial \Psi_{\beta}}{\partial x'} \frac{\partial \gamma_{\beta}}{\partial u'} - \frac{\partial \gamma_{\beta}}{\partial x'} \frac{\partial \Psi_{\beta}}{\partial u'} \right] dz dz'$$

Variation

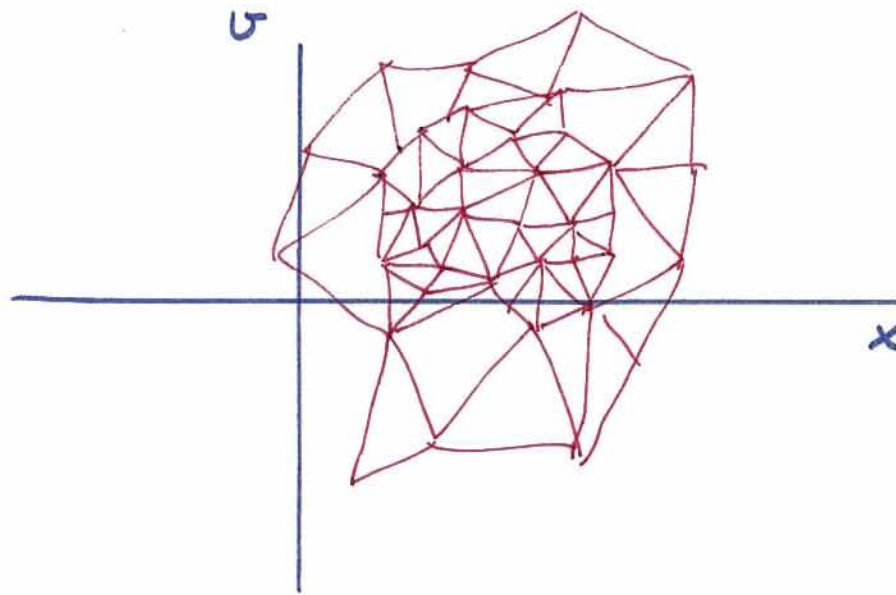
$$\delta J = \frac{d}{d\epsilon} J(\Psi_{\alpha} + \epsilon w) \Big|_{\epsilon=0} = 0$$

yields equations
above.

$$w = 0 \text{ on } \partial D \subset \mathbb{R}^4$$

Rayleigh - Ritz

Break phase space up into finite elements



Tailor element size for accuracy.

Define ψ_x & \mathcal{I}_x at each Node.

$$\Psi_\alpha = \sum_i N_i^\alpha(t) G(z-z_i) \quad \& \quad \Gamma_\alpha = \sum_i \eta_i^\alpha(t) G(z-z_i)$$

(e.g. $G(z-z_i) = G(x-x_i)G(u-u_i)$
where G is a tent function)

J becomes

$$J = \sum_\alpha \int dt \left\{ \sum_{i,j} \eta_j^\alpha \frac{dN_i^\alpha}{dt} A_{ij} - \sum_{i,j} \eta_j^\alpha N_i^\alpha B_{ij} + \sum_\beta \sum_{i,j,k,r} C_{ijkr} N_i^\alpha N_k^\beta \eta_j^\alpha \eta_r^\beta \right\}$$

Variation of J yields a finite set of ordinary differential equations

$$\frac{d\eta_j^\alpha}{dt} = \dots$$

$$\frac{dN_i^\alpha}{dt} = \dots$$

(11)

$$A_{ij} = \int dz \ G(z-z_i) G(z-z_j)$$

$$B_{ij} = \int \frac{1}{2} m_a v^2 \{ G(z-z_i), G(z-z_j) \} dz$$

$$C_{ijk\ell} = \int dz dz' \frac{e_x e_\beta}{2} K(x|x') \{ G(z-z_i), G(z-z_j) \} \\ \times \{ G(z'-z_k), G(z'-z_\ell) \}$$

Caveats

- * Equations are Hyperbolic \Rightarrow
Extremal \neq Extremum
(May still be stable)
- * The Potentials Ψ & \mathcal{I} will probably wind
up which will require relabeling.
- * will $\int f dz$ be conserved