

Simple harmonic motion (Section 15.1)

1. SHM: From initial x and v to A and ϕ
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4. Mass–spring: Projection of circular motion

Kinetic energy and potential energy in SHM (Section 15.3)

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Simple pendulum and physical pendulum (Section 15.4)

6. Physical pendulum
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Consider a simple harmonic motion (SHM) along the x axis centered about the origin. The displacement x and velocity v are given by the following (see Eq. (15.4) with δ replaced by ϕ):

$$x = A \cos(\omega t + \phi) \text{ and } v = dx/dt = -A\omega \sin(\omega t + \phi).$$

At $t = 0$,

$$x = x_0 \text{ and } v = v_0.$$

Determine the amplitude A :

	A
A	x_0
B	$\frac{\omega}{v_0}$
C	$\sqrt{x_0^2 + \left(\frac{\omega}{v_0}\right)^2}$

Hint: At $t = 0$ there are two equations:

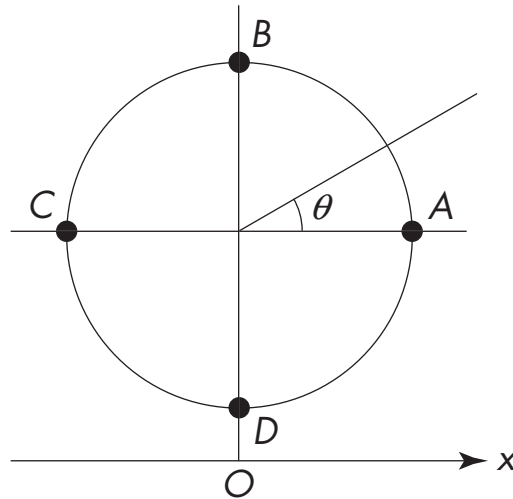
$$x_0 = A \cos \phi. \quad (1)$$

$$v_0 = -\omega A \sin \phi. \quad (2)$$

Extra: Express ϕ in terms of x_0 and v_0 .

Explanation: This is the situation of two equations (1) and (2) with two unknowns: A and ϕ . Using $\cos^2 \phi + \sin^2 \phi = 1$, we may eliminate ϕ . More specifically, $(A \cos \phi)^2 + (A \sin \phi)^2 = x_0^2 + (v_0/\omega)^2 = A^2$. Solving for A leads to Answer = C.

Explanation—extra: Taking the ratio of Eq. (2) and (1) leads to the elimination of A : $\tan \phi = \sin \phi / \cos \phi = -(v_0/\omega)/x_0 = -v_0/(\omega x_0)$.

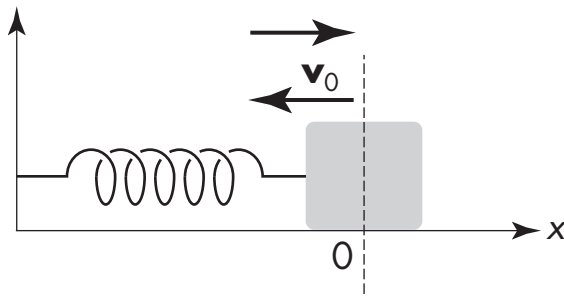


Consider a simple harmonic motion (SHM) $x = A \cos \theta$ as a projection of a uniform circular motion with $\theta = \omega t + \phi$. If at $t = 0$, $x = 0$ and $v = v_0 > 0$, determine ϕ :

	Point on the circle	ϕ
A	A	0
B	B	90°
C	C	180°
D	D	270°

Hint: Consider both of the initial conditions $x = 0$ and $v_0 > 0$.

Explanation: Because $x = 0$ when $t = 0$, we may choose either B or D . Notice that at B the velocity is along the negative x direction. But at D the velocity is along the positive x direction. So D is the correct choice—that is, at $t = 0$, $\theta = \phi = 270^\circ$. Answer = D .



Consider a mass–spring system in which the mass oscillates according to simple harmonic motion: $x = A \cos(\omega t + \phi)$. At $t = 0$ the mass is at the equilibrium position moving to the left. Determine the phase angle ϕ :

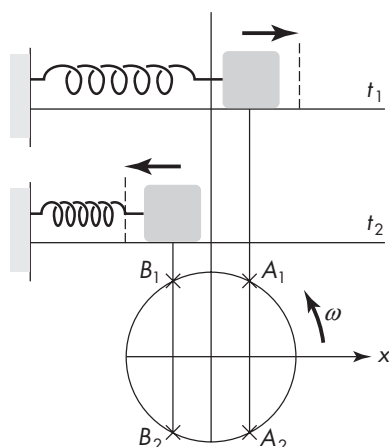
	ϕ
A	0
B	$\pi/2$
C	π
D	$3\pi/2$

Hint: $v = dx/dt = -\omega A \sin(\omega t + \phi)$.

Extra: Find an expression for the amplitude A of the periodic motion in terms of the maximum speed v_0 and the angular velocity ω .

Explanation: From the given information at $t = 0$, $x = 0 = A \cos \phi$, and $v = -|v_0| = -\omega A \sin \phi$. Because $\cos \phi = 0$, we have $\phi = \pi/2$ or $3\pi/2$. From the velocity equation, $|v_0| = \omega A \sin \phi$. This implies that $\sin \phi$ must be positive. In other words, $\phi = \pi/2$ is the correct choice. Answer = B.

Explanation—extra: The velocity equation gives $A = |v_0|/(\omega \sin \phi) = |v_0|/\omega$.



Consider the mass–spring system shown here at two different time t_1 and t_2 , where the mass oscillates according to simple harmonic motion: $x = A \cos(\omega t + \phi)$. The motion is modeled as the projection of the circular motion shown at the bottom. Locate the point on the circle that corresponds to the time t_1 :

At t_1	
A	A_1
B	A_2

Hint: Consider both the position and the velocity.

Extra: Which point on the circle corresponds to moment B ?

Explanation: At the time t_1 , as far the location of the mass is concerned, both A_1 and A_2 are possible. Because the velocity at moment A is positive, it limits the point A_2 to be the correct choice. Answer = B.

Explanation—extra: At the time t_2 , the velocity of the mass is negative. By inspection, B_1 is the correct choice.

Consider a mass–spring system in which the oscillation is described by $x = A \cos \omega t$. The kinetic energy is $K = m(dx/dt)^2/2$. The potential energy is $U = kx^2/2$. The maxima are $K_{\max} = m(\omega A)^2/2$ and $U_{\max} = kA^2/2$. Which choice here gives the total energy of oscillation?

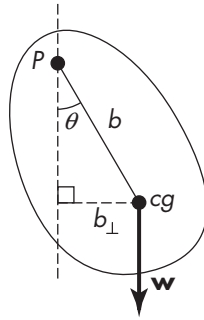
- | | |
|---|---|
| A | $E = K_{\max} = U_{\max} = m(\omega A)^2/2$ |
| B | $E = K_{\max} + U_{\max} = m(\omega A)^2$ |
| C | $E = K_{\max} + U_{\max} = kA^2$ |

Extra: At which point during the oscillation do you expect the mass–spring system to have the most energy?

- When the spring is relaxed (at $x = 0$).
- When the spring is fully stretched (at $|x| = x_{\max}$).

Explanation: The total energy $E = K + U$ of the mass–spring system is a conserved quantity. E remains at the same value throughout the oscillations. When the mass passes the point $x = 0$, its potential energy is 0 and its kinetic energy is at its maximum. At the maximum stretch, its potential energy is at its maximum and its kinetic energy is 0. Answer = A.

Explanation—extra: Because E stays the same throughout the oscillations, the total energy of the mass–spring system at $x = 0$ is the same as the total energy at $|x| = x_{\max}$.



Consider a physical pendulum of mass m where P is the pivot point and b is the distance between P and the center of gravity. In a small θ approximation, $b_{\perp} = b \sin \theta \approx b\theta$, and the equation of motion is given by

$$\tau = I\alpha = Id^2\theta/dt^2 = -mgb \sin \theta \approx -(mgb)\theta \quad (1)$$

Determine the period T of this physical pendulum:

	A	B	C	D
T	$\sqrt{\frac{I}{\kappa}}$	$2\pi\sqrt{\frac{I}{mgb}}$	$\sqrt{\frac{\kappa}{I}}$	$2\pi\sqrt{\frac{mgb}{I}}$

Hint: For simple harmonic motion,

$$d^2s/dt^2 = -\omega^2s \quad (2)$$

with $\omega = 2\pi/T$.

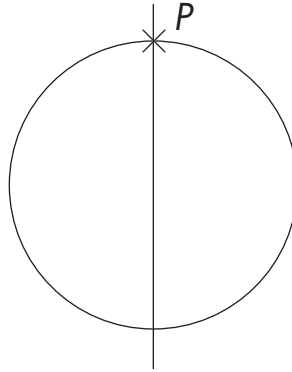
Extra: Find T of a simple pendulum that has a mass m and a length L .

Explanation: Comparing the equations of motion (1) and (2) with $\theta = s$ implies that $\omega^2 = mgb/I$. This leads to

$$T = \frac{2\pi}{\omega} = 2\pi\sqrt{\frac{I}{mgb}}. \text{ Answer = B.}$$

Explanation—extra: For a simple pendulum, $I = mL^2$ and $b = L$. So

$$T = 2\pi\sqrt{\frac{L}{g}}.$$



The period of a physical pendulum is $T = 2\pi \sqrt{\frac{I}{mgb}}$, where m is the mass, I is the moment of inertia about the pivot point, and b is the distance between the pivot point and the center of gravity. Consider a circular loop oriented vertically where the pivot point P is at the top of the loop (see the sketch). Find b and I for a loop with radius r and mass m :

	A	B	C	D
b	r	r	$2r$	$2r$
I	mr^2	$2mr^2$	mr^2	$2mr^2$

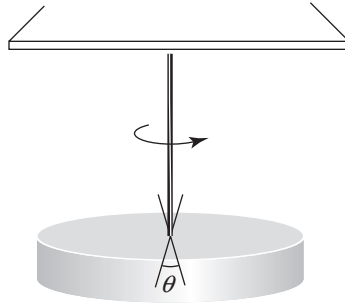
Hint: Use the parallel axis theorem: $I = I_{\text{cm}} + MD^2$.

Extra: Find the period T of the oscillation of the loop.

Explanation: b is the distance between P and the center, so $b = r$.

$I = I_{\text{cm}} + MD^2 = mr^2 + mr^2 = 2mr^2$. Answer = B.

Explanation—extra: $T = 2\pi \sqrt{\frac{I}{mgb}} = 2\pi \sqrt{\frac{2mr^2}{mgr}} = 2\pi \sqrt{\frac{2r}{g}}$.



A circular disk is suspended by a wire attached at the top of some fixed support. When the disk is twisted through some small angle θ , the twisted wire exerts a restoring torque on the body that satisfies $\tau = I\alpha = I d^2\theta/dt^2 = -\kappa\theta$, where κ is referred to as the *torsion constant* of the wire. Find the period of the oscillation:

	A	B	C	D
T	$\sqrt{\frac{I}{\kappa}}$	$2\pi\sqrt{\frac{I}{\kappa}}$	$\sqrt{\frac{\kappa}{I}}$	$2\pi\sqrt{\frac{\kappa}{I}}$

Hint: For simple harmonic motion, $d^2s/dt^2 = -\omega^2s$, with $\omega = 2\pi/T$.

Explanation: The present equation of motion implies that $\omega^2 = \kappa/I$, and in turn, $2\pi\sqrt{\frac{I}{\kappa}}$. Answer = B.