The metriplectic 4-bracket: a curvature-like framework for describing dissipation in joined Hamiltonian and dissipative fluid and plasma

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Collaborators: G. Flierl, M. Furukawa, <u>C. Bressan</u>, O. Maj, M. Kraus, E. Sonnendrücker; T. Ratiu, A. Bloch, B. Coquinot & M. Materassi. Geometry of metriplectic 4-brackets: with Michael Updike

pjm & M. Updike, arXiv:2306.06787v1 [math-ph] 11 Jun 2023.

→ Theory of thermodynamically consistent theories!

Theories & Models → Dynamics

Goal:

Predict the future or explain the past \Rightarrow

$$\dot{z} = V(z)$$
, $z \in \mathcal{Z}$, Phase Space

A dynamical system. Maps, ODEs, PDEs, etc.

Whence vector field V?

- Fundamental parent theory (microscopic, N interacting gravitating or charged particles, BBGKY hierarchy, Vlasov-Maxwell system, ...). Identify small parameters, rigorous asymptotics \rightarrow Reduced Computable Model V.
- <u>Phenomena</u> based modeling using known properties, constraints, etc. used to intuit \rightarrow

Reduced Computable Model V. \leftarrow structure can be useful.

Types of Vector Fields, V(z) (cont)

Only (?) Natural Split:

$$V(z) = V_H + V_D$$

- Hamiltonian vector fields, V_H : conservative, properties, etc.
- Dissipative vector fields, V_D : not conservative of something, relaxation/asymptotic stability, etc.

General Hamiltonian Form:

finite dim
$$\rightarrow$$
 $V_H = J \frac{\partial H}{\partial z}$ or $V_H = \mathcal{J} \frac{\delta H}{\delta \psi} \leftarrow \infty$ dim

where J(z) is Poisson tensor/operator and H is the Hamiltonian. Basic product decomposition.

General Dissipation:

Why investigate? General properties of theory. Build in thermodynamic consistency. Geometry? Useful for computation.

Codifying Dissipation – Some History

Is there a framework for dissipation akin to the Hamiltonian formulation for nondissipative systems?

Rayleigh (1873):
$$\frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{q}_{\nu}} \right) - \left(\frac{\partial \mathcal{L}}{\partial q_{\nu}} \right) + \left(\frac{\partial \mathcal{F}}{\partial \dot{q}_{\nu}} \right) = 0$$

Linear dissipation e.g. of sound waves. Theory of Sound.

Cahn-Hilliard (1958):
$$\frac{\partial n}{\partial t} = \nabla^2 \frac{\delta \mathcal{F}}{\delta n} = \nabla^2 \left(n^3 - n - \nabla^2 n \right)$$

Phase separation, nonlinear diffusive dissipation, binary fluid ...

Other Gradient Flows:
$$\frac{\partial \psi}{\partial t} = \mathcal{G} \frac{\delta \mathcal{F}}{\delta \psi}$$

Otto, Ricci Flows, Poincarè conjecture on S^3 , Perelman (2002)...

Metriplectic Dynamics

(Metric ∪ Symplectic Flows)

- Formalism for natural split of vector fields
- Enforces thermodynamic consistency: $\dot{H}=0$ the 1st Law and $\dot{S}>0$ the 2nd Law.
- Other invariants? E.g., collision operators preserve, mass, momentum, There exists some theory for building in, but won't discuss today.
- Encompassing 4-bracket theory: "curvature" as dissipation

Ideas of Casimirs are candidates for entropy, multibracket, curvature, etc. in pjm (1984). Metriplectic in pjm (1986).

Hamilton's Canonical Equations

Phase Space with Canonical Coordinates: (q, p)

Hamiltonian function: $H(q,p) \leftarrow \text{the energy}$

Equations of Motion:

$$\dot{p}_{\alpha} = -\frac{\partial H}{\partial q^{\alpha}}, \qquad \dot{q}^{\alpha} = \frac{\partial H}{\partial p_{i}}, \qquad \alpha = 1, 2, \dots N$$

Phase Space Coordinate Rewrite: z = (q, p), i, j = 1, 2, ... 2N

$$\dot{z}^i = J_c^{ij} \frac{\partial H}{\partial z^j} = \{z^i, H\}_c, \qquad (J_c^{ij}) = \begin{pmatrix} 0_N & I_N \\ -I_N & 0_N \end{pmatrix},$$

 $J_c := \underline{\text{Poisson tensor}}$, Hamiltonian bi-vector, cosymplectic form

Noncanonical Hamiltonian Structure

Sophus Lie (1890) \longrightarrow PJM (1980) \longrightarrow Poisson Manifolds etc.

Noncanonical Coordinates:

$$\dot{z}^i = \{z^i, H\} = J^{ij}(z) \frac{\partial H}{\partial z^j}$$

Noncanonical Poisson Bracket:

$$\{f,g\} = \frac{\partial f}{\partial z^i} J^{ij}(z) \frac{\partial g}{\partial z^j}$$

Poisson Bracket Properties:

antisymmetry
$$\longrightarrow$$
 $\{f,g\} = -\{g,f\}$
Jacobi identity \longrightarrow $\{f,\{g,h\}\} + \{b,\{h,f\}\} + \{h,\{f,g\}\} = 0$
Leibniz \longrightarrow $\{fh,g\} = f\{h,g\} + \{h,g\}f$

G. Darboux: $det J \neq 0 \implies J \rightarrow J_c$ Canonical Coordinates

Sophus Lie: $det J = 0 \Longrightarrow$ Canonical Coordinates plus <u>Casimirs</u> (Lie's distinguished functions!)

Poisson Brackets – Flows on Poisson Manifolds

Definition. A Poisson manifold \mathcal{Z} has bracket

$$\{\,,\,\}:C^{\infty}(\mathcal{Z})\times C^{\infty}(\mathcal{Z})\to C^{\infty}(\mathcal{Z})$$

st $C^{\infty}(\mathcal{Z})$ with $\{,\}$ is a Lie algebra realization, i.e., is

- bilinear,
- antisymmetric,
- Jacobi, and
- Leibniz, i.e., acts as a derivation ⇒ vector field.

Geometrically $C^{\infty}(\mathcal{Z}) \equiv \Lambda^{0}(\mathcal{Z})$ and d exterior derivative.

$$\{f,g\} = J(df \wedge dg) = \langle df, Jdg \rangle = J(df, dg).$$

J the Poisson tensor/operator. Flows are integral curves of non-canonical Hamiltonian vector fields, JdH, i.e.,

$$\dot{z}^i = J^{ij}(z) \frac{\partial H(z)}{\partial z^j}, \qquad \mathcal{Z}'s \text{ coordinate patch } z = (z^1, \dots, z^N)$$

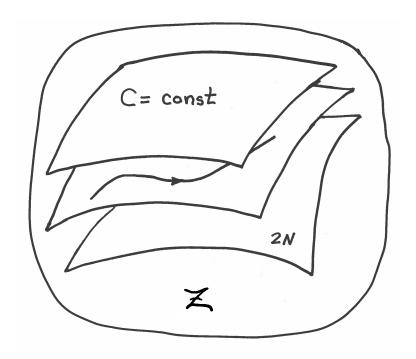
Because of degeneracy, \exists functions C st $\{f,C\}=0$ for all $f\in C^{\infty}(\mathcal{Z})$. Casimir invariants (Lie's distinguished functions!).

Poisson Manifold (phase space) \mathcal{Z} Cartoon

Degeneracy in $J \Rightarrow \text{Casimirs}$:

$$\{f,C\} = 0 \quad \forall \ f: \mathcal{Z} \to \mathbb{R}$$

Lie-Darboux Foliation by Casimir (symplectic) leaves:



Metriplectic 4-Bracket: (f, k; g, n)

Why a 4-Bracket?

- \bullet Two slots for two fundamental functions: Hamiltonian, H, and Entropy (Casimir), S.
- There remains two slots for bilinear bracket: one for observable one for generator $(\mathcal{F}?)$ s.t. $\dot{H}=0$ and $\dot{S}\geq0$.
- Provides natural reductions to other bilinear & binary brackets.
- The three slot brackets of pjm 1984 were not trilinear. Four needed to be multilinear.

The Metriplectic 4-Bracket

4-bracket on 0-forms (functions):

$$(\,\cdot\,,\,\cdot\,;\,\cdot\,,\,\cdot\,)\colon \Lambda^0(\mathcal{Z})\times \Lambda^0(\mathcal{Z})\times \Lambda^0(\mathcal{Z})\times \Lambda^0(\mathcal{Z})\to \Lambda^0(\mathcal{Z})$$

For functions $f, k, g, n \in \Lambda^0(\mathcal{Z})$

$$(f,k;g,n) := R(df,dk,dg,dn),$$

In a coordinate patch the metriplectic 4-bracket has the form:

$$(f,k;g,n) = R^{ijkl}(z) \frac{\partial f}{\partial z^i} \frac{\partial k}{\partial z^j} \frac{\partial g}{\partial z^k} \frac{\partial n}{\partial z^l}.$$
 \leftarrow quadravector?

- ullet A blend of my previous ideas: Two important functions H and S, symmetries, curvature idea, multilinear brackets.
- ullet Manifolds with both Poisson tensor, J^{ij} , and compatible quadravector R^{ijkl} , where S and H come from Hamiltonian part.

Metriplectic 4-Bracket Properties

(i) linearity in all arguments, e.g,

$$(f+h,k;g,n) = (f,k;g,n) + (h,k;g,n)$$

(ii) algebraic identities/symmetries

$$(f, k; g, n) = -(k, f; g, n)$$

 $(f, k; g, n) = -(f, k; n, g)$
 $(f, k; g, n) = (g, n; f, k)$
 $(f, k; g, n) + (f, g; n, k) + (f, n; k, g) = 0$ \leftarrow not needed

(iii) derivation in all arguments, e.g.,

$$(fh, k; g, n) = f(h, k; g, n) + (f, k; g, n)h$$

which is manifest when written in coordinates. Here, as usual, fh denotes pointwise multiplication. Symmetries of algebraic curvature without cyclic identity. Often see R^l_{ijk} or R_{lijk} but not R^{lijk} ! Minimal Metriplectic.

Early Binary 2-Brackets and Dissipation

Ingredients:

Binary Brackets (Poisson and Dissipative) + Generators

$$\dot{z} = \{z, H\} + ((z, \mathcal{F}))$$

If $((\cdot, \cdot))$ Leibniz & bilinear

$$\dot{z}^i = J^{ij} \frac{\partial H}{\partial z^j} + G^{ij} \frac{\partial \mathcal{F}}{\partial z_j}$$

where

$$((,)): C^{\infty}(\mathcal{Z}) \times C^{\infty}(\mathcal{Z}) \to C^{\infty}(\mathcal{Z})$$

What is \mathcal{F} and what are the algebraic properties of ((,))?

Metriplectic 2-Bracket

(pjm 1984,1984,1986)

- \bullet (f,g) symmetric, bilinear, appropriately degenerate
- <u>Casimirs</u> of noncanonical PB $\{,\}$ <u>are 'candidate' entropies</u>. Election of particular $S \in \{\text{Casimirs}\} \Rightarrow \text{thermodynamic equilibrium (relaxed) state.}$
- Generator: $\mathcal{F} = H + S$ \leftarrow "Free Energy"
- 1st Law: identify energy with Hamiltonian, H, then

$$\dot{H} = \{H, \mathcal{F}\} + (H, \mathcal{F}) = 0 + (H, H) + (H, S) = 0$$

Foliate \mathcal{Z} by level sets of H, with $(H, f) = 0 \ \forall \ f \in C^{\infty}(\mathcal{Z})$.

• 2nd Law: entropy production

$$\dot{S} = \{S, \mathcal{F}\} + (S, \mathcal{F}) = (S, S) \ge 0$$

Lyapunov relaxation to the equilibrium state. Dynamics solves the equilibrium variational principle: $\delta \mathcal{F} = \delta(H+S) = 0$.

Metriplectic 4-Bracket Reduction to 2-Bracket

Symmetric 2-bracket:

$$(f,g)_H = (f,H;g,H) = (g,f)_H$$

Dissipative dynamics:

$$\dot{z} = (z, S)_H = (z, H; S, H)$$

Energy conservation:

$$(g,H)_H = (H,g)_H = 0 \qquad \forall g.$$

Entropy dynamics:

$$\dot{S} = (S, S)_H = (S, H; S, H) \ge 0$$

Metriplectic 4-brackets → metriplectic 2-brackets of 1984, 1986!

Metriplectic 4-Bracket: Encompassing Definition of Dissipation

• Lots of geometry on Poisson manifolds with metric or connection. Emerges naturally.

• If Riemannian, entropy production rate is positive contravariant sectional curvature. For $\sigma, \eta \in \Lambda^1(\mathcal{Z})$, entropy production by

$$\dot{S} = K(\sigma, \eta) := (S, H; S, H),$$

where the second equality follows if $\sigma = dS$ and $\eta = dH$.

Binary Brackets for Dissipation circa 1980 \rightarrow

- Symmetric Bilinear Brackets (pjm 1980 . . . , IFS report 1983, published 1984 reduced MHD)
- Antisymmetric Bracket (possibly degenerate) (Kaufman and pjm 1982)
- Metriplectic Dynamics (pjm 1984, 1984, 1986, ... Kaufman 1984 had no degeneracy)
- GENERIC (Grmela 1984, with Oettinger 1997, ...) Binary but **not** Symmetric and **not** Bilinear ⇔ Metriplectic Dynamics!
- Double Brackets (Vallis, Carnevale, Young, Shepherd; Brockett, Bloch ... 1989)

4-Bracket Reduction to K-M Brackets

(Kaufman and Morrison 1982)

K-M done for plasma quasilinear theory.

Dynamics:

$$\dot{z} = [z, H]_S = (z, H; S, H)$$

Bracket Properties:

$$[f,g]_S = (f,g;S,H)$$

- bilinear
- antisymmetric, possibly degenerate
- energy conservation and entropy production

$$\dot{H} = [H, H]_S = 0$$
 and $\dot{S} = [S, H]_S \ge 0$ \Rightarrow $z \mapsto z_{eq}$

4-Bracket Reduction to Double Brackets

(Vallis, Carnevale; Brockett, Bloch ... 1989)

Interchanging the role of H with a Casimir S:

$$(f,g)_S = (f,S;g,S)$$

Can show with assumptions (Koszul construction)

$$(C,g)_S = (C,S;g,S) = 0$$

for any Casimir C. Therefore $\dot{C} = 0$.

Practical tool for equilibria computation \rightarrow Beautiful geometry with Fernandes-Koszul connection!

4-Bracket Reduction to 2-Brackets GENERIC

(Grmela 1984, with Öttinger 1997)

• Grmela 1984 bracket for Boltzmann <u>not bilinear</u> and <u>not symmetric</u>, unlike metriplectic 2-bracket.

GENERIC Vector Field in terms of dissipation function $\Xi(z,z_*)$:

$$\dot{z}^i = Y_S^i = \frac{\partial \Xi(z, z_*)}{\partial z_{*i}} \bigg|_{z_* = \partial S/\partial z}$$
.

Special Case:

$$\Xi(z,z_*) = \frac{1}{2} \frac{\partial S}{\partial z^i} G^{ij}(z) \frac{\partial S}{\partial z^j} \quad \Rightarrow \quad Y_S^i = G^{ij}(z) \frac{\partial S}{\partial z^j},$$

ullet General Case: there exists a bracket and procedure (pjm & Updike) for linearizing and symmetrizing \Rightarrow

GENERIC (1997) \equiv Metriplectic (1984,1986)!

Existence – General Constructions

- For any Riemannian manifold ∃ metriplectic 4-bracket. This means there is a wide class of them, but the bracket tensor does not need to come from Riemann tensor only needs to satisfy the bracket properties.
- Methods of construction? We describe two, Kulkarni-Nomizu and Lie algebra based. Goal is to develop intuition like building Lagrangians.

Construction via Kulkarni-Nomizu Product

Given σ and μ , two symmetric rank-2 tensor fields operating on 1-forms (assumed exact) df, dk and dg, dn, the K-N product is

$$\sigma \otimes \mu (\mathbf{d}f, \mathbf{d}k, \mathbf{d}g, \mathbf{d}n) = \sigma(\mathbf{d}f, \mathbf{d}g) \mu(\mathbf{d}k, \mathbf{d}n) - \sigma(\mathbf{d}f, \mathbf{d}n) \mu(\mathbf{d}k, \mathbf{d}g) + \mu(\mathbf{d}f, \mathbf{d}g) \sigma(\mathbf{d}k, \mathbf{d}n) - \mu(\mathbf{d}f, \mathbf{d}n) \sigma(\mathbf{d}k, \mathbf{d}g).$$

Metriplectic 4-bracket:

$$(f, k; g, n) = \sigma \otimes \mu(\mathbf{d}f, \mathbf{d}k, \mathbf{d}g, \mathbf{d}n).$$

In coordinates:

$$R^{ijkl} = \sigma^{ik}\mu^{jl} - \sigma^{il}\mu^{jk} + \mu^{ik}\sigma^{jl} - \mu^{il}\sigma^{jk}.$$

Lie Algebras and Lie-Poisson Brackets

<u>Lie-Poisson Brackets:</u> special noncanonical Poisson brackets associated with any Lie algebra, \mathfrak{g} .

Natural phase space \mathfrak{g}^* . For $f,g\in C^{\infty}(\mathfrak{g}^*)$ and $z\in\mathfrak{g}^*$.

Lie-Poisson bracket has the form

Pairing <, $>: \mathfrak{g}^* \times \mathfrak{g} \to \mathbb{R}$, z^i coordinates for \mathfrak{g}^* , and c^{ij}_{k} structure constants of \mathfrak{g} . Note

$$J^{ij} = c^{ij}_{k} z_k \,.$$

Lie Algebra Based Metriplectic 4-Brackets

• For structure constants c^{kl}_{s} :

$$(f, k; g, n) = c^{ij}{}_r c^{kl}{}_s g^{rs} \frac{\partial f}{\partial z^i} \frac{\partial k}{\partial z^j} \frac{\partial g}{\partial z^k} \frac{\partial n}{\partial z^l}.$$

Lacks cyclic symmetry, but \exists procedure to remove torsion (Bianchi identity) for any symmetric 'metric' g^{rs} . Dynamics does not see torsion, but manifold does.

 \bullet For $g^{rs}_{CK}=c^{rl}_{\ k}\,c^{sk}_{\ l}$ the Cartan-Killing metric, torsion vanishes automatically. Completely determined by Lie algebra.

Examples

- finite-dimensional
- 1+1 fluid theory
- 3+1 fluid theory
- kinetic theory

Free Rigid Body

Angular momenta (L^1, L^2, L^3) , Lie-Poisson bracket with Lie algebra $\mathfrak{so}(3)$, $c^{ij}_{\ k} = -\epsilon_{ijk}$.

Hamiltonian:

$$H = \frac{(L^1)^2}{2I_1} + \frac{(L^2)^2}{2I_2} + \frac{(L^3)^2}{2I_3}$$

principal moments of inertia, I_i Casimir

$$C = ||L||^2 = (L^1)^2 + (L^3)^2 + (L^3)^2 = S$$

Euler's equations:

$$\dot{L}^i = \{L^i, H\}$$

"Thermodynamics" \rightarrow design a system s.t. $\dot{H} = 0$ and $\dot{S} \leq 0$.

"Thermodynamical" Free Rigid Body

Use K-N product. Choose $\sigma^{ij} = \mu^{ij} = g^{ij} \Rightarrow$

$$R^{ijkl} = K \left(g^{ik} g^{jl} - g^{il} g^{jk} \right) ,$$

Riemannian *Space form* with constant sectional curvature K.

Assume Euclidean gives metriplectic 4-bracket:

$$(f, k; g, n) = K \left(\delta^{ik} \delta^{jl} - \delta^{il} \delta^{jk} \right) \frac{\partial f}{\partial z^i} \frac{\partial k}{\partial z^j} \frac{\partial g}{\partial z^k} \frac{\partial n}{\partial z^l},$$

Metriplectic 2-bracket:

$$(f,g)_H = (f,H;g,H)$$

Precisely bracket and dynamics of pjm 1986!

$$\dot{L}^i = \{L^i, H\} + (L^i, S)_H = \{L^i, H\} + (L^i, H; S, H)$$

1D fluid u(x,t)

Again use K-N product with operators Σ and M

$$(F, K; G, N) = \int_{\mathbb{R}} dx \, W \Big(\Sigma(F_u, G_u) M(K_u, N_u) \\ - \Sigma(F_u, N_u) M(K_u, G_u) + M(F_u, G_u) \Sigma(K_u, N_u) \\ - M(F_u, N_u) \Sigma(K_u, G_u) \Big),$$

W a constant and $F_u = \delta F/\delta u$, etc. Choose

$$M(F_u, G_u) = F_u G_u$$

$$\Sigma(F_u, G_u)(x) = \partial F_u(x) \mathcal{H}[G_u](x) + \partial G_u(x) \mathcal{H}[F_u](x),$$

 $\partial = \partial/\partial x$ and \mathcal{H} the Hilbert transform \Rightarrow

$$(F,G)_H = (F,H;G,H) = \int_{\mathbb{R}} dx \, W \Big(\partial F_u \mathcal{H}[G_u] + \partial G_u \mathcal{H}[F_u] \Big) \, .$$

$$u_t = ...(u, S)_H = -2W \mathcal{H}[\partial u].$$

Ott & Sudan 1969 fluid model of electron Landau damping (Hammett-Perkins 1990). $\mathcal{H} \rightarrow \partial \Rightarrow$ viscous dissipation

Thermodynamic Navier-Stokes:

$$\chi = \{\rho, \sigma = \rho s, M = \rho v\}$$

K-N again:

$$M(F_{\chi}, G_{\chi}) = F_{\sigma}G_{\sigma}$$

$$\Sigma(F_{\chi}, G_{\chi}) = \widehat{\Lambda}_{ijkl} \, \partial_j F_{M_i} \partial_k G_{M_l} + a \, \nabla F_{\sigma} \cdot \nabla G_{\sigma}$$

 $\partial_i := \partial/\partial x^i$ with general isotropic Cartesian tensor of order 4

$$\hat{\Lambda}_{ikst} = \alpha \delta_{ik} \delta_{st} + \beta (\delta_{is} \delta_{kt} + \delta_{it} \delta_{ks}) + \gamma (\delta_{is} \delta_{kt} - \delta_{it} \delta_{ks})$$

Construct

$$(F,G)_H = (F,H;G,H) \rightarrow \chi_t = \{\chi,H\} + (\chi,S)_H \Rightarrow$$

using $S = \int d^3x \, \rho s$ and $H = \int d^3x \left(\rho |\mathbf{v}|^2 / 2 + \rho U(\rho,s)\right)$

$$\partial_{t} \boldsymbol{v} = -\boldsymbol{v} \cdot \nabla \boldsymbol{v} - \frac{1}{\rho} \nabla p + \frac{1}{\rho} \nabla \cdot \mathcal{T}$$

$$\partial_{t} \rho = -\nabla \cdot (\rho \boldsymbol{v})$$

$$\partial_{t} s = -\boldsymbol{v} \cdot \nabla s - \frac{1}{\rho T} \nabla \cdot \boldsymbol{q} + \frac{1}{\rho T} \mathcal{T} : \nabla \boldsymbol{v}, \qquad \boldsymbol{q} = -\kappa \nabla T$$

Reproduces pjm 1984!

Collision Operator

Phase space z = (x, v), density f(z, t)

Define operator on $w: \mathbb{R}^6 \to \mathbb{R}$ (at fixed time)

$$P[w]_i = \frac{\partial w(z)}{\partial v_i} - \frac{\partial w(z')}{\partial v_i'}$$

$$(F, K; G, N) = \int d^6 z \int d^6 z' \mathcal{G}(z, z') \times (\delta \otimes \delta)_{ijkl} P \left[F_f \right]_i P \left[K_f \right]_j P \left[G_f \right]_k P \left[N_f \right]_l,$$

where simplest K-N

$$(\delta \otimes \delta)_{ijkl} = 2(\delta_{ik}\delta_{jl} - \delta_{il}\delta_{jk}).$$

with $S = -\int d^2 f \ln f$

$$(f, H; SH) = ??$$

Landau-Lenard-Balescu collision operator!

Metriplectic 2-bracket $(f,g)_H$ in pjm 1984 again!

Theory Final Comments

- See PJM & M. Updike, arXiv:2306.06787v1 [math-ph] 11 Jun
 2023 for many more examples, finite and infinite.
- Useful for thermodynamically consistent model building, e.g., multiphase flow (Navier-Stokes-Cahn-Hiliard) with many constitutive relation effects (with A. Zaidni) and inhomogeneous collision operator (with N. Sato).
- Given that double brackets and metriplectic brackets have been used for computation of equilibria, metriplectic 4-bracket can be a new tool for equilibria.
- New kind of structure to preserve: Symplectic, Poisson, FEEC,
 metriplectic 2-bracket, metriplectic 4-bracket?
- Ideas re deep learning, layered neural networks, etc.

Existing Computational Uses

• Poisson Integrators: symplectic on leaf and exact leaf preservation; GEMPIC, Kraus et al. for Vlasov-Maxwell system. B. Jayawardana, P. J. Morrison, and T. Ohsawa, Clebsch Canonization of Lie-Poisson Systems, J. Geometric Mechanics 14, 635 (2022).

Dynamical extremization with constraints:

- Simulated Annealing: Double brackets for equilibria
- Metriplectic relaxation

Double Bracket for Vortex States 1989

Good Idea:

Vallis, Carnevale, and Young, Shepherd (1989,1990)

$$\frac{d\mathcal{F}}{dt} = \{\mathcal{F}, H\} + ((\mathcal{F}, H)) = ((\mathcal{F}, \mathcal{F})) \ge 0$$

where

$$((F,G)) = \int d^3x \, \frac{\delta F}{\delta \chi} \mathcal{J}^2 \frac{\delta G}{\delta \chi}$$

Lyapunov function, \mathcal{F} , yields asymptotic stability to rearranged equilibrium.

• <u>Maximizing</u> energy at fixed Casimir: Except only works sometimes, e.g., limited to circular vortex states

Simulated Annealing

Use various bracket dynamics to effect extremization.

Many relaxation methods exist: gradient descent, etc.

Simulated annealing: an **artificial** dynamics that solves a variational principle with constraints for equilibria states.

Coordinates:

$$\dot{z}^i = ((z^i, H)) = J^{ik} g_{kl} J^{jl} \frac{\partial H}{\partial z^j}$$

symmetric, definite, and kernel of J.

$$\dot{C} = 0$$
 with $\dot{H} \leq 0$

Simulated Annealing with Generalized (Noncanonical) Dirac Brackets

Dirac Bracket:

$$\{F,G\}_D = \{F,G\} + \frac{\{F,C_1\}\{C_2,G\}}{\{C_1,C_2\}} - \frac{\{F,C_2\}\{C_1,G\}}{\{C_1,C_2\}}$$

Preserves any two incipient constraints C_1 and C_2 .

Our New Idea:

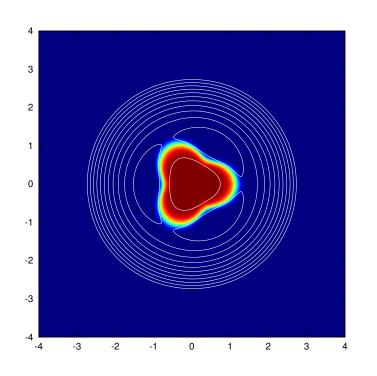
Do simulated Annealing with Generalized Dirac Bracket

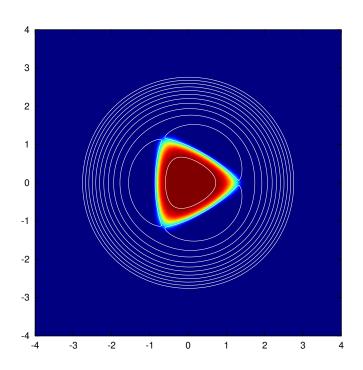
$$((F,G))_D = \int d\mathbf{x} d\mathbf{x}' \{F, \zeta(\mathbf{x})\}_D \ \mathcal{G}(\mathbf{x}, \mathbf{x}') \ \{\zeta(\mathbf{x}'), G\}_D$$

Preserves any Casimirs of $\{F,G\}$ and Dirac constraints $C_{1,2}$

For implementation with contour dynamics see PJM (with Flierl) Phys. Plasmas 12 058102 (2005).

2D Euler Vortex States (Flierl and pjm 2011)





Vorticity contours. The three-fold symmetric initial condition finds tri-polar state using Dirac bracket Simulated Annealing.

Double Bracket SA for Reduced MHD

M. Furukawa, T. Watanabe, pjm, and K. Ichiguchi, *Calculation of Large-Aspect-Ratio Tokamak and Toroidally-Averaged Stellarator Equilibria of High-Beta Reduced Magnetohydrodynamics via Simulated Annealing*, Phys. Plasmas **25**, 082506 (2018).

High-beta reduced MHD (Strauss, 1977) given by

$$\frac{\partial U}{\partial t} = [U, \varphi] + [\psi, J] - \epsilon \frac{\partial J}{\partial \zeta} + [P, h]$$

$$\frac{\partial \psi}{\partial t} = [\psi, \varphi] - \epsilon \frac{\partial \varphi}{\partial \zeta}$$

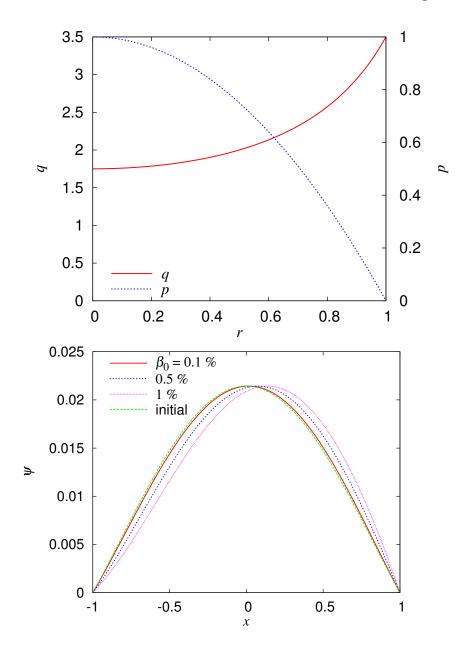
$$\frac{\partial P}{\partial t} = [P, \varphi]$$

Extremization

 $\mathcal{F} = H + \sum_{i} C_i + \lambda^i P_i$, \rightarrow equilibria, maybe with flow

Cs Casimirs and Ps dynamical invariants.

Sample Double Bracket SA equilibria



Nested Tori are level sets of ψ ; q gives pitch of helical \boldsymbol{B} -lines.

Double Bracket SA for Stability

M. Furukawa and P. J. Morrison, *Stability analysis via simulated annealing and accelerated relaxation*, Phys. Plasmas, 2022.

Since SA searches for an energy extremum, it can also be used for stability analysis when initiated from a state where a perturbation is added to an equilibrium. Three steps:

- 1) choose any equilibrium of unknown stability
- 2) perturb the equilibrium with dynamically accessible (leaf) perturbation
- 3) perform double bracket SA

If it finds the equilibrium, then is is an energy extremum and must be stable

Sample Double Bracket SA unstable equilibria

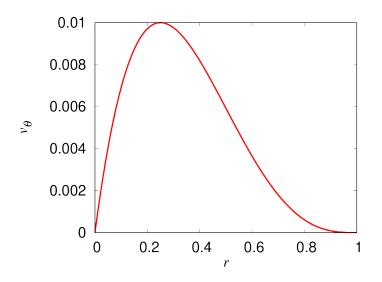
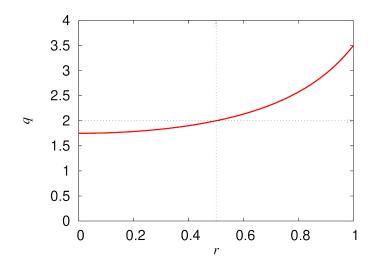
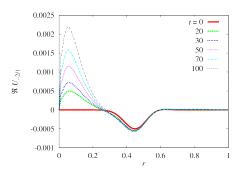
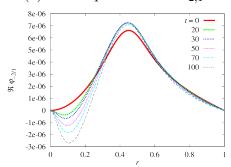


FIG. 12: Poloidal rotation velocity v_{θ} profile.

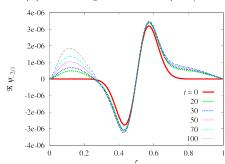




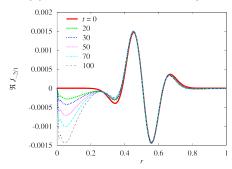
(a) Radial profile of $\Re U_{-2,1}$.



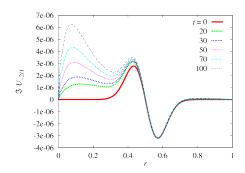
(c) Radial profile of $\Re \varphi_{-2,1}$.



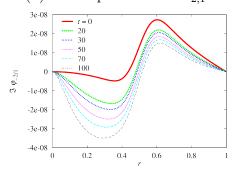
(e) Radial profile of $\Re \psi_{-2,1}$.



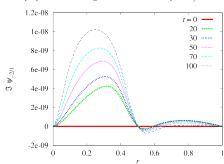
(g) Radial profile of $\Re J_{-2,1}$.



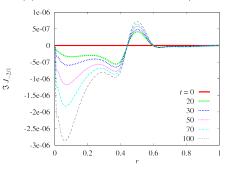
(b) Radial profile of $\Im U_{-2,1}$.



(d) Radial profile of $\Im \varphi_{-2,1}$.



(f) Radial profile of $\Im \psi_{-2,1}$.



(h) Radial profile of $\Im J_{-2,1}$.

Metriplectic Simulated Annealing.

Camilla Bressen Ph.D.

TUM & Max Planck, Garching, Germany

Vortex states and MHD equilibria

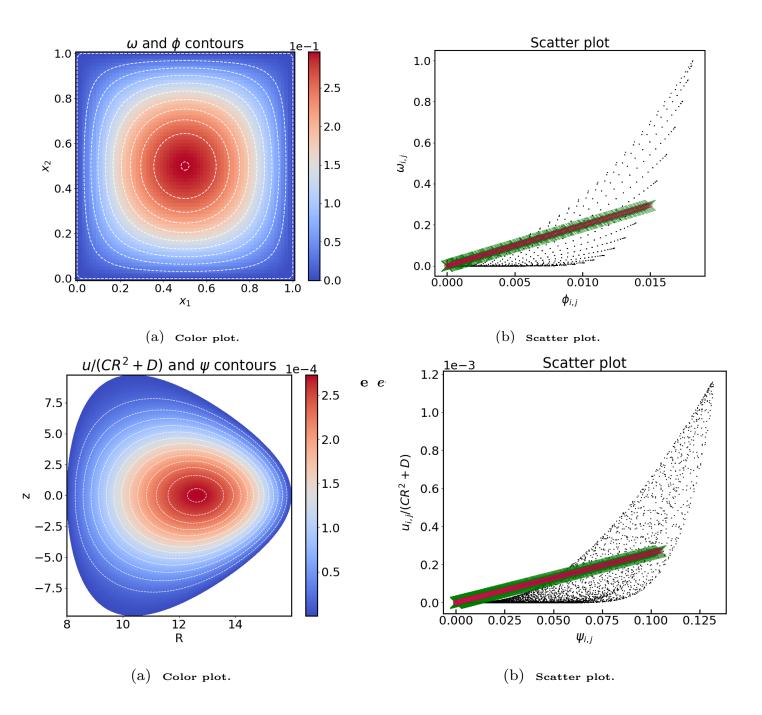


Figure 6.29: Relaxed state for the gs-imgc test case. The same as in Figure 6.23, but for the collision-like operator and the case of the Czarny domain discussed in Section A.4.2. With respect to Figure 6.27(b) for the diffusion-like operator, we see from (b) that the agreement between the relaxed state and the prediction of the variational principle is better.

Computation Summary

- Poisson Integrators
- Dirac Double Bracket Simulated Annealing for Equilibria and Stability
- Metriplectic Simulated Annealing for Equilibria

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